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Revisions & Change Log			
Rev	Description	Date	Approved
X1	Initial Draft	Oct 18	Chung
X2	Feedbacks Implemented	Oct 22	Chung
X3	Feedbacks from Chung Implemented	Oct 23	Chung
X4	Components changed as per the feedbacks	Oct 24	Chung
X5	RF and Bluetooth headers added	Oct 28	Chung
X6	Arduino connections added	Nov 1	Chung
X7	Net review and fix	Nov 3	Chung
A	Release to production, prototype build	Nov 8	Chung
A1	openSDA reset capacitor fix	Nov 22	del Rey
B	Release to production, production build	Jan 20	Chung
C	Release to production, production build	Feb 06	Chung
D	Fixing I2C swap to headers	Feb 26	Chung
D1	Enhancing USB PWR input filter for robustness	Mar 18	Chung
E	Swapping J2.2 connection to PTC12 Fix Eth Link status when 2 FRDMs are connected to each other	Jul 11	Chung
E1	Updating J13 Ethernet connector part	Sep 03	Chung
E2	Depopulating J14	Sep 10	Chung
E3	Depopulating C55, populating R75	Oct 14	Chung
E4	Some Net alias renaming Title block update	15-Apr-16	M. Byma

FREEDOM K64F

		Microcontroller Product Group 6501 William Cannon Drive West Austin, TX 78735-8598	
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ICAP Classification: CP: IUC: X PUBI: X			
Designer: Rafael del Rey	Drawing Title: FRDM-K64F		
Drawn by: Sudhasha(LNT)	Page Title: TITLE PAGE		
Approved: Chung	Size C	Document Number SCH-28163 PDF: SPF-28163	Rev E4
Date: Friday, April 15, 2016 Sheet 1 of 7			

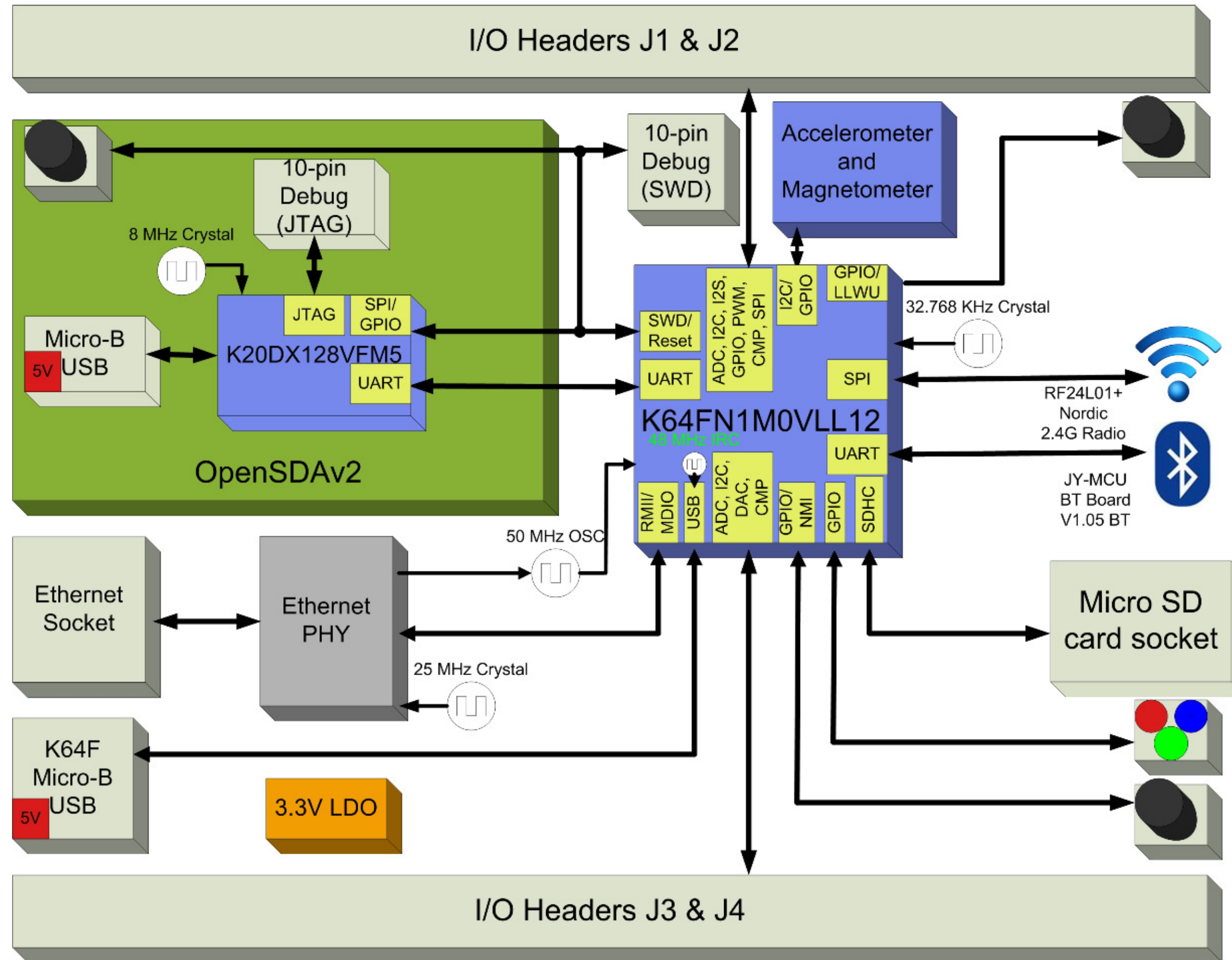
- Unless Otherwise Specified:
 All resistors are in ohms, most are 1%, 1/10 Watt. Otherwise are 5%, 1/8 Watt.
 All capacitors are in uF, some are 10% or 20%
 All voltages are DC
 All polarized capacitors are tantalum

- Interrupted lines coded with the same letter or letter combinations are electrically connected.

- Device type number is for reference only. The number varies with the manufacturer.

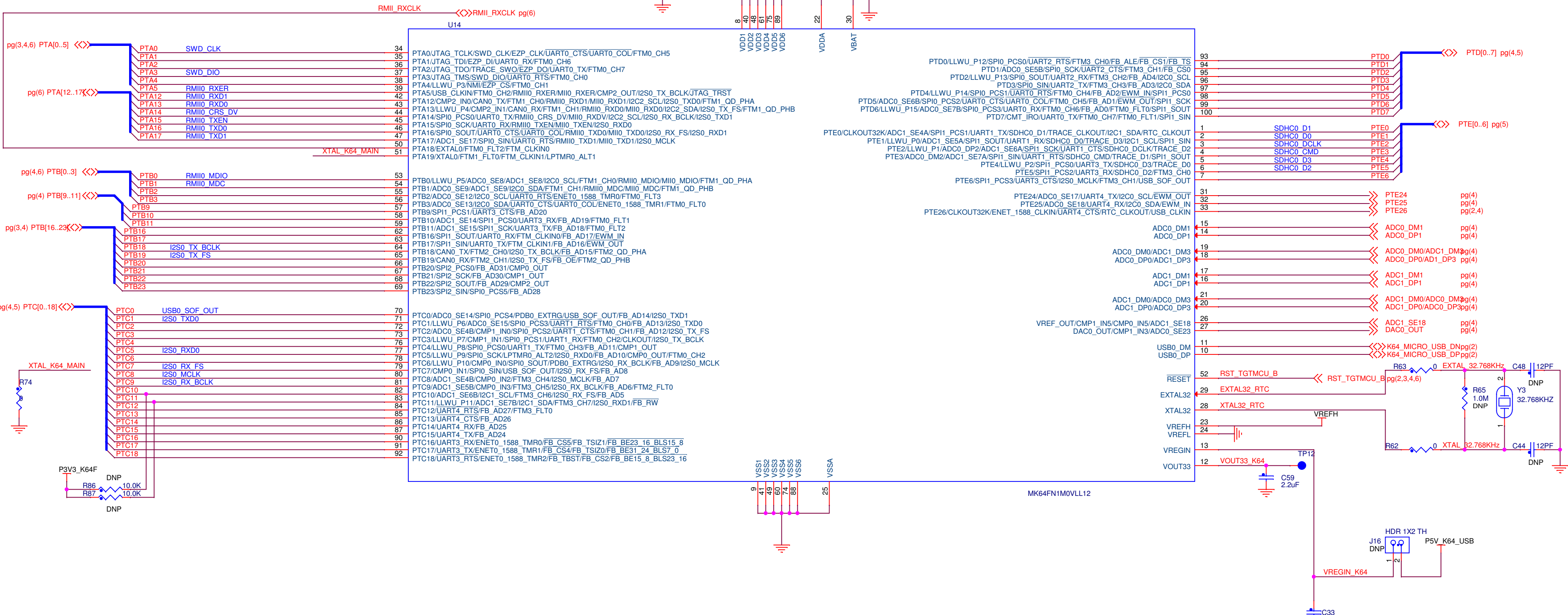
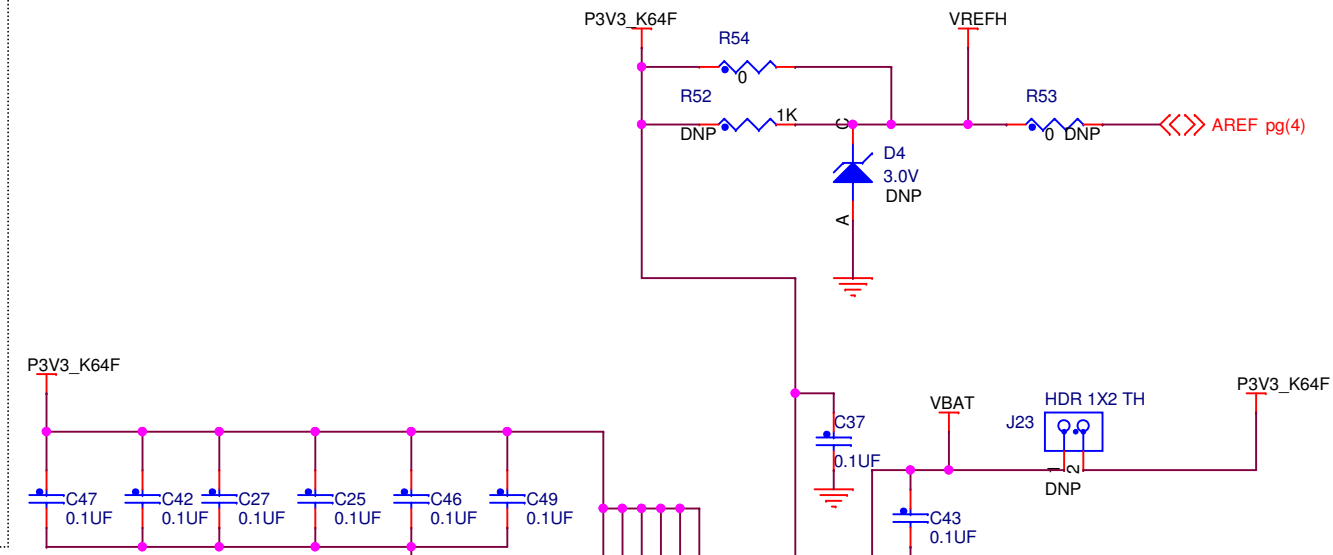
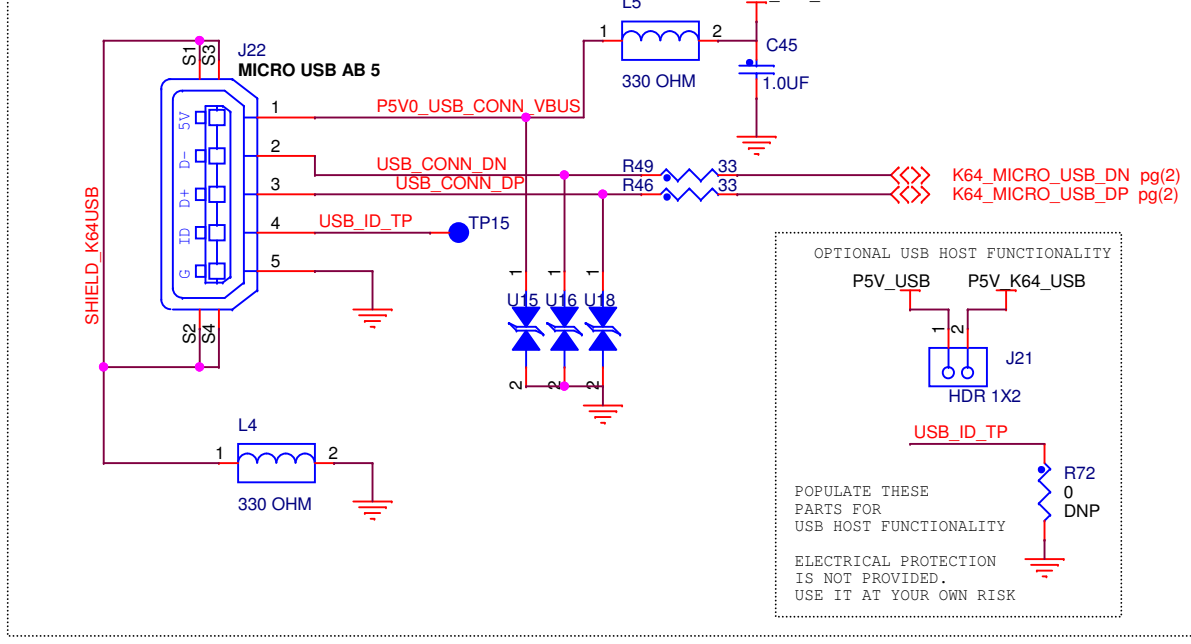
- Special signal usage:
 _B Denotes - Active-Low Signal
 <> or [] Denotes - Vectored Signals

- Interpret diagram in accordance with American National Standards Institute specifications, current revision, with the exception of logic block symbology.

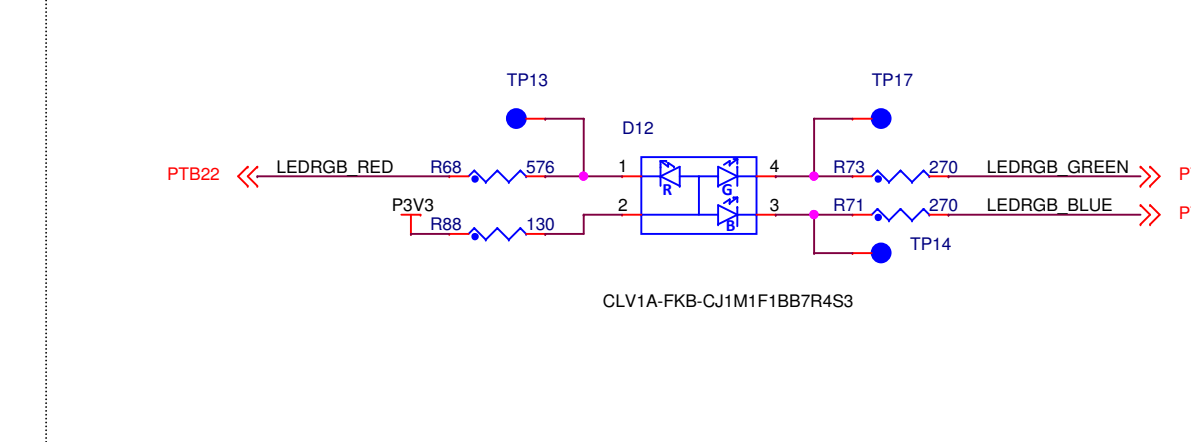


ICAP Classification:	CP:	IUO: X	PUBI:
Drawing Title:	FRDM-K64F		
Page Title:	BLOCK DIAGRAM		
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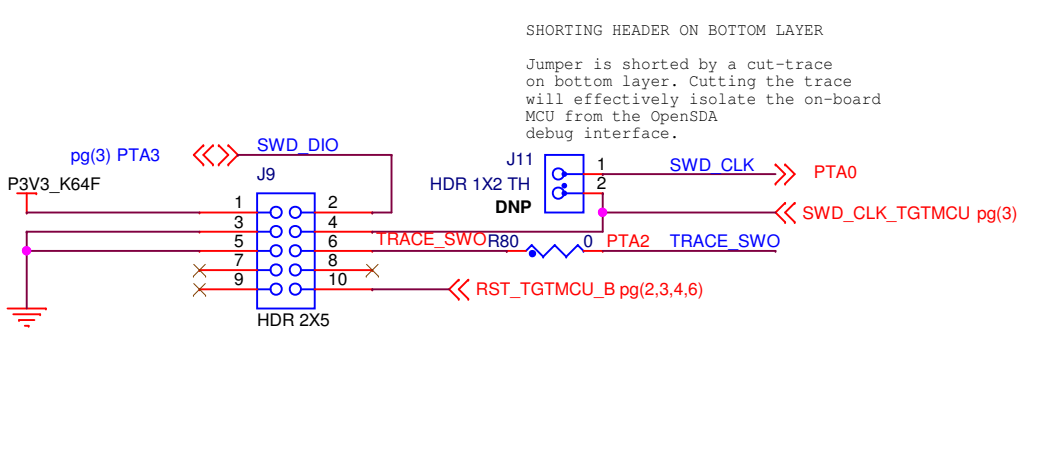
K64F USB CONNECTOR



RGB LED FEATURE

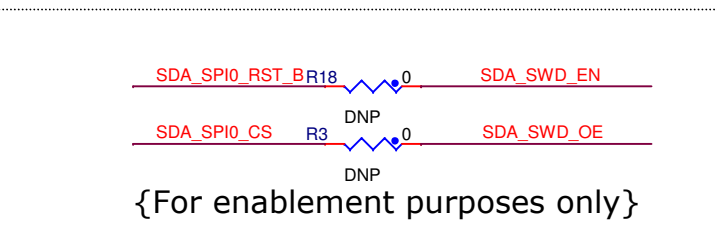
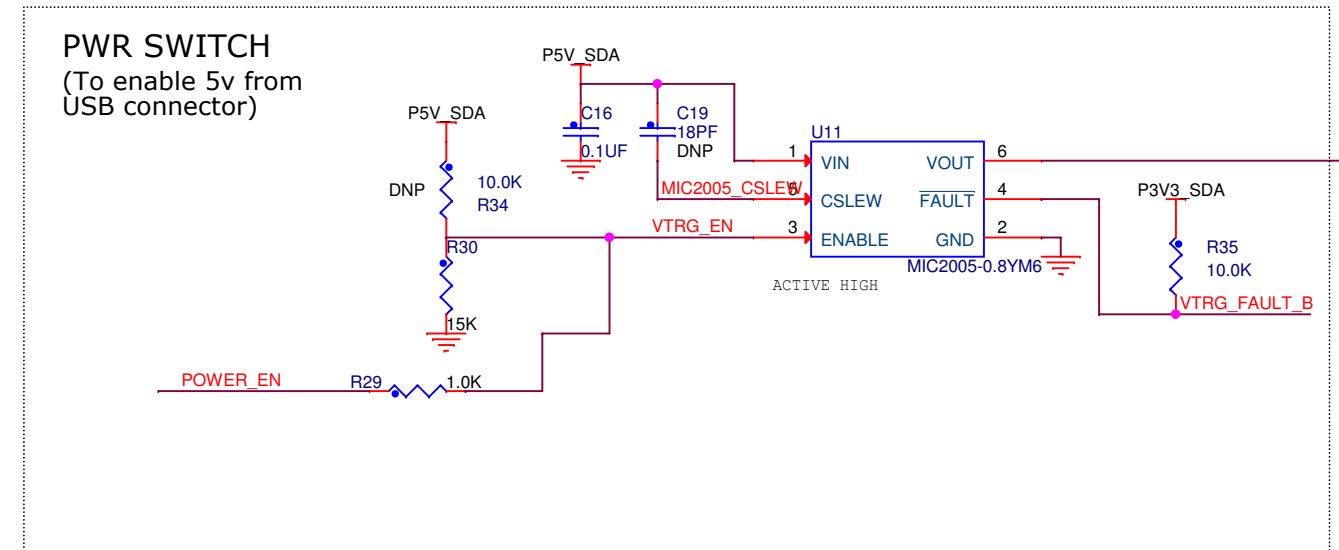
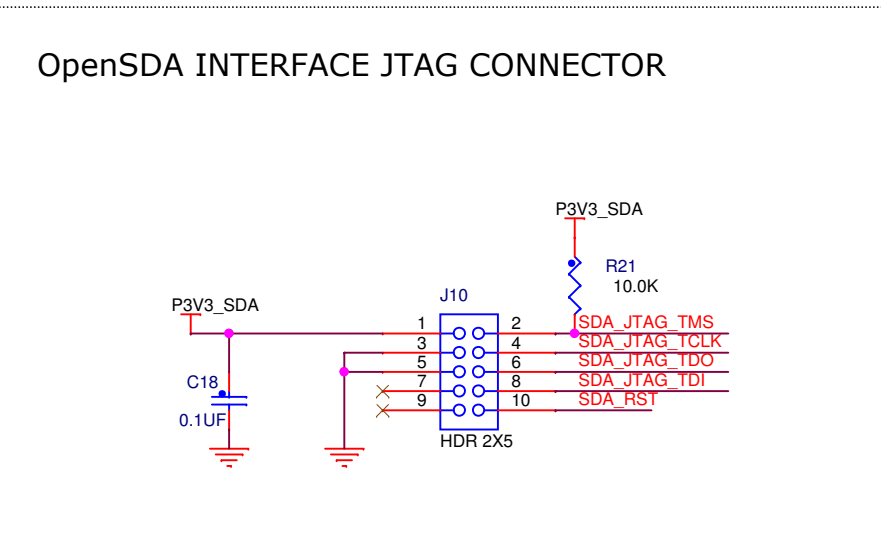
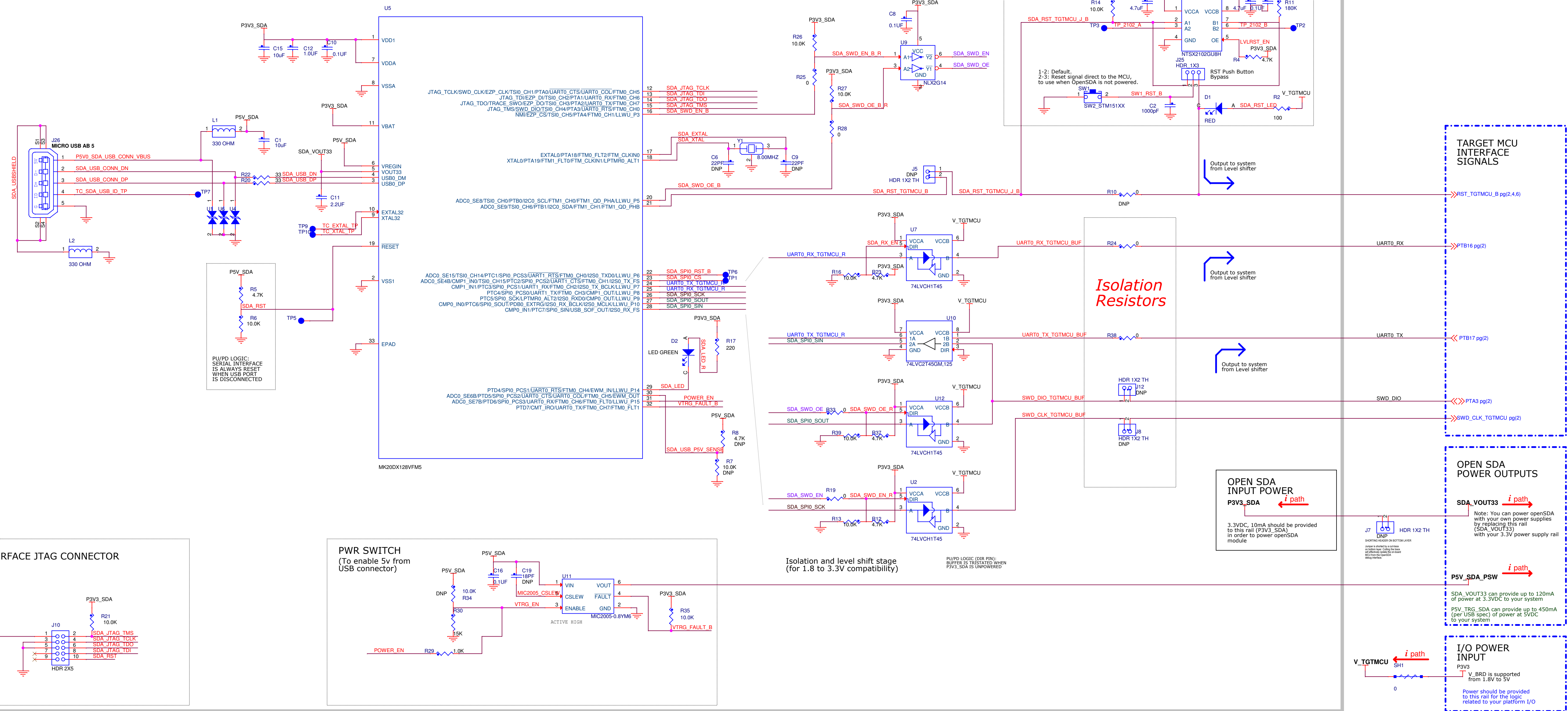


SWD CONNECTOR



ICAP Classification:	CP:	IUO:	PUBI: X
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OpenSDA Interface



OPEN SDA INPUT POWER
P3V3_SDA

3.3VDC, 10mA should be provided to this rail (P3V3_SDA) in order to power OpenSDA module

OPEN SDA POWER OUTPUTS

SDA_VOUT33 *i path*

Note: You can power OpenSDA with your own power supplies by replacing this rail (SDA_VOUT33)

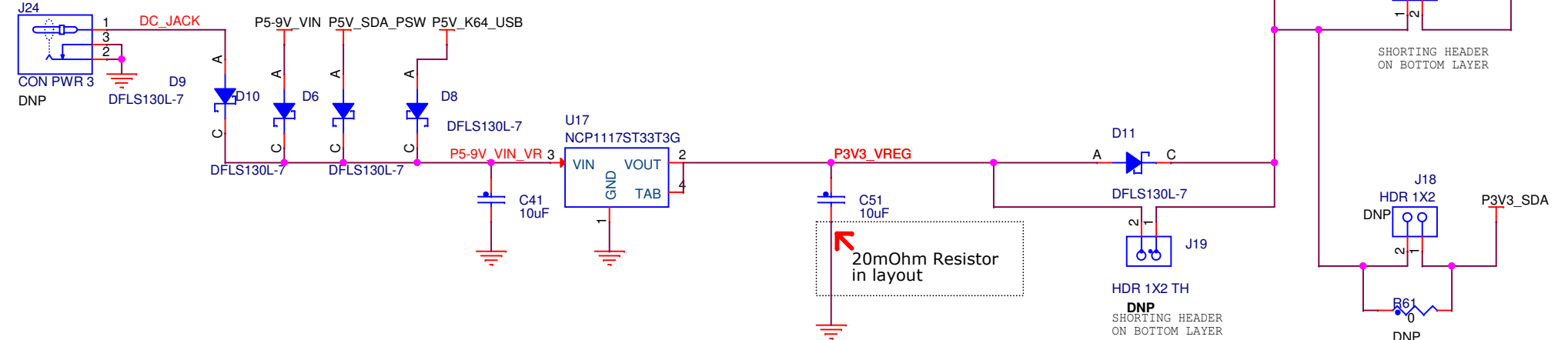
PSV_SDA_PSW *i path*

SDA_VOUT33 can provide up to 120mA of power at 3.3VDC to your system
PSV_SDA_PSW can provide up to 450mA (per USB spec) of power at 5VDC to your system

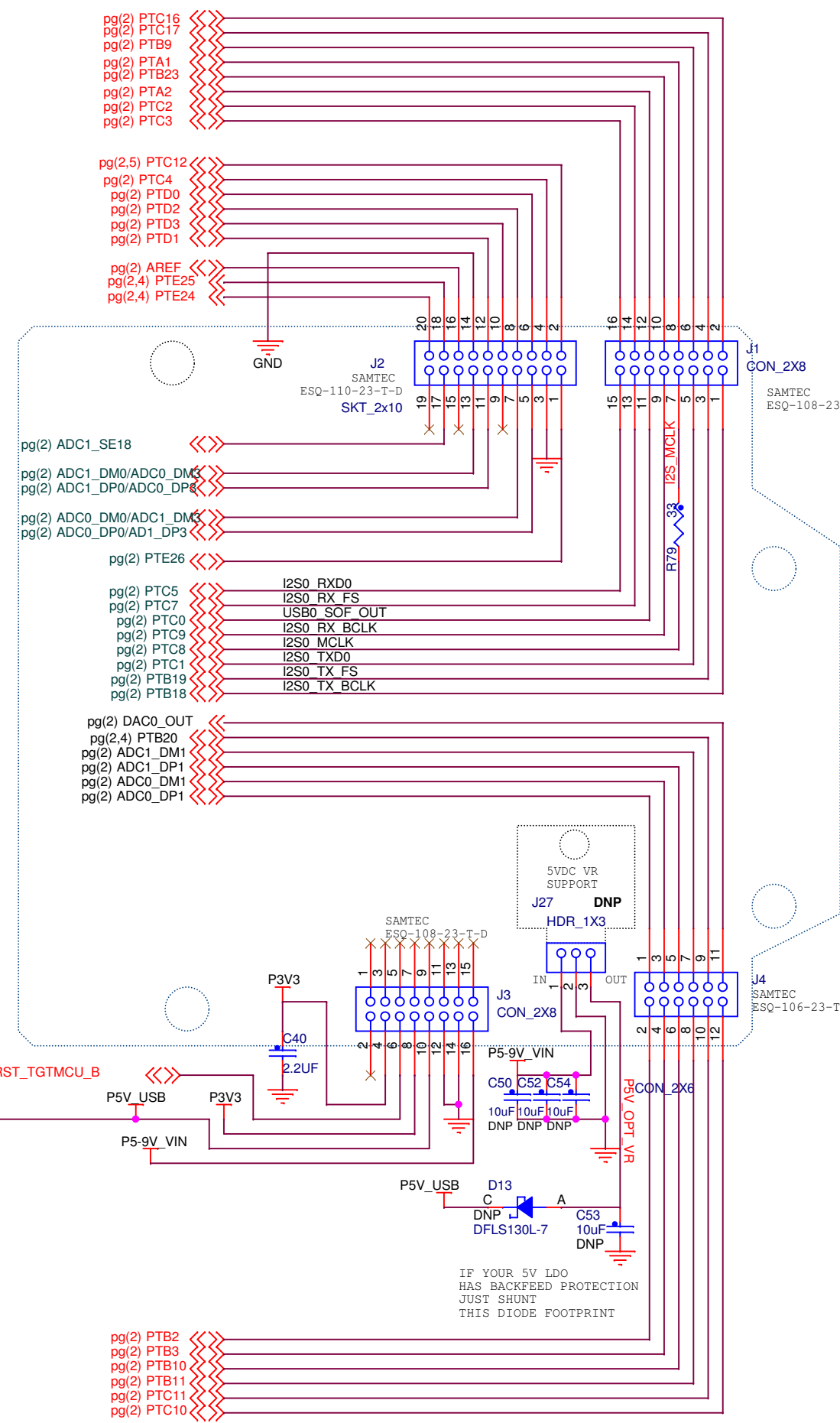
I/O POWER INPUT

V_TGTMCU

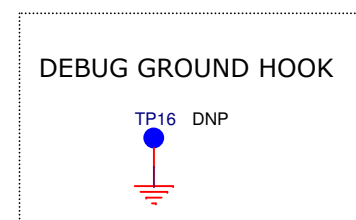
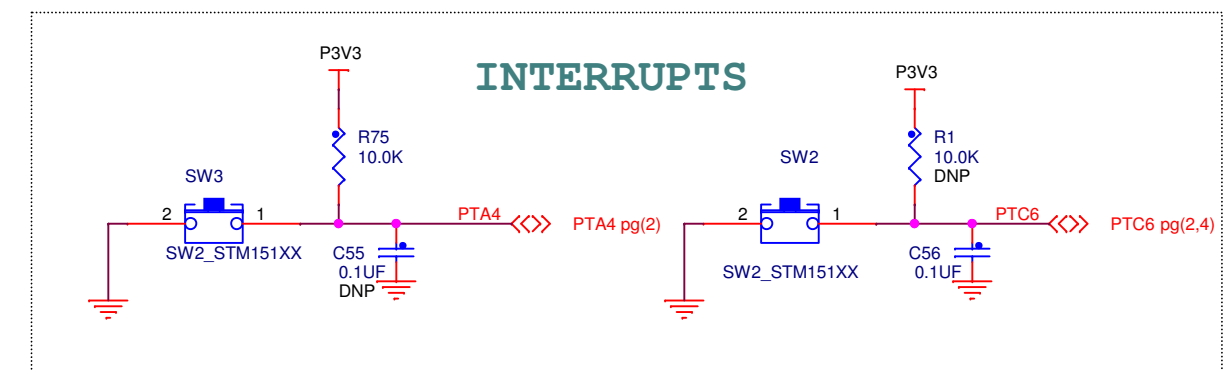
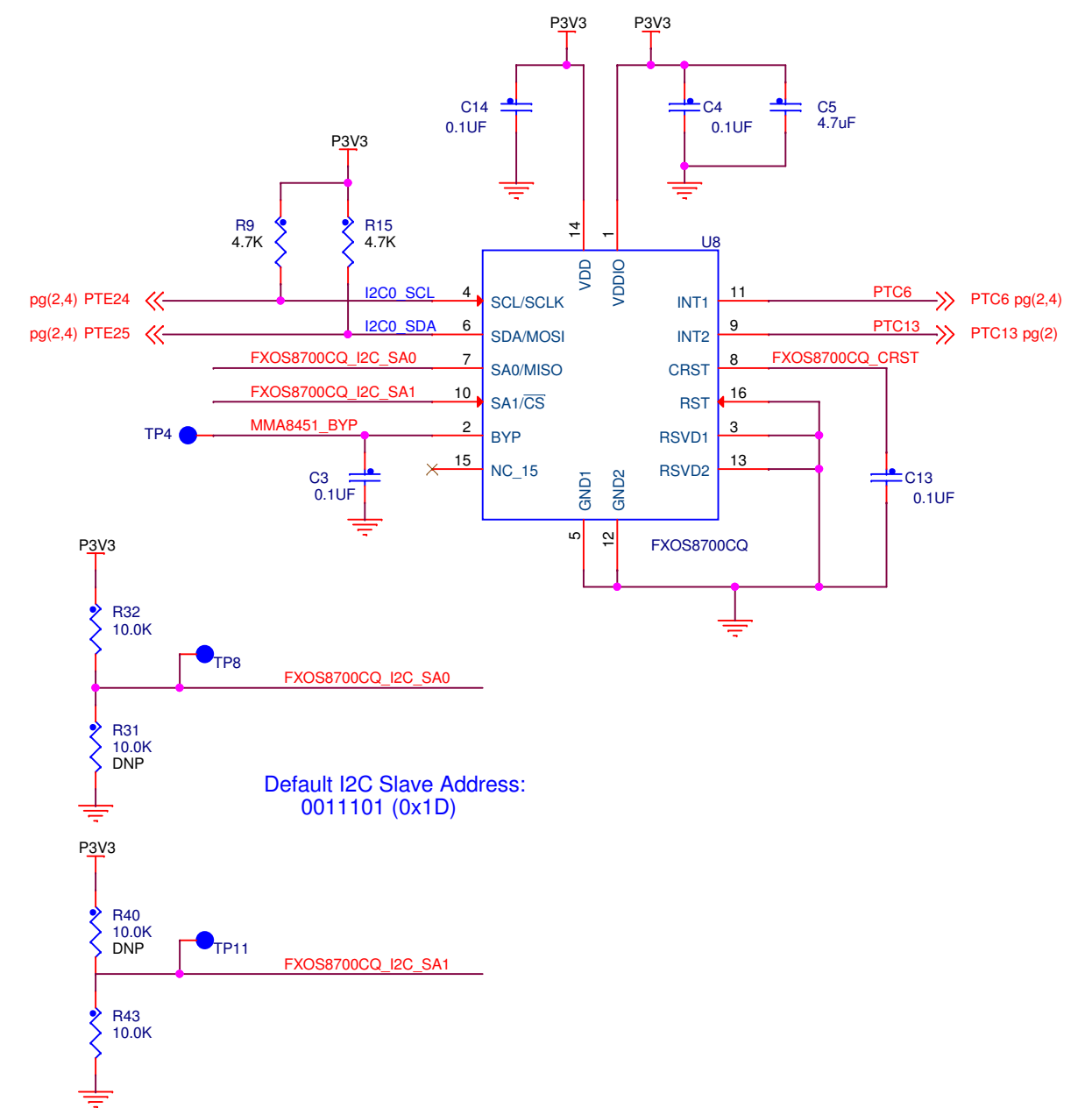
V_BRD is supported from 1.8V to 5V
Power should be provided to this rail for the logic related to your platform I/O



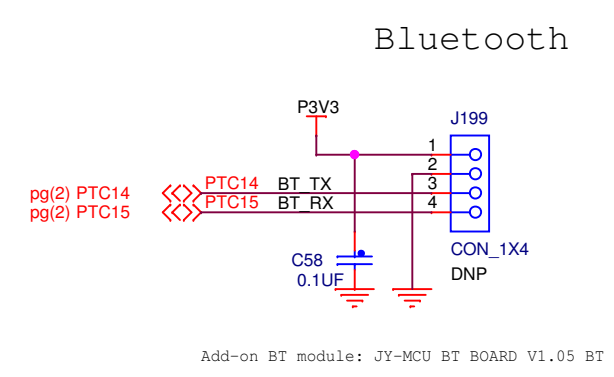
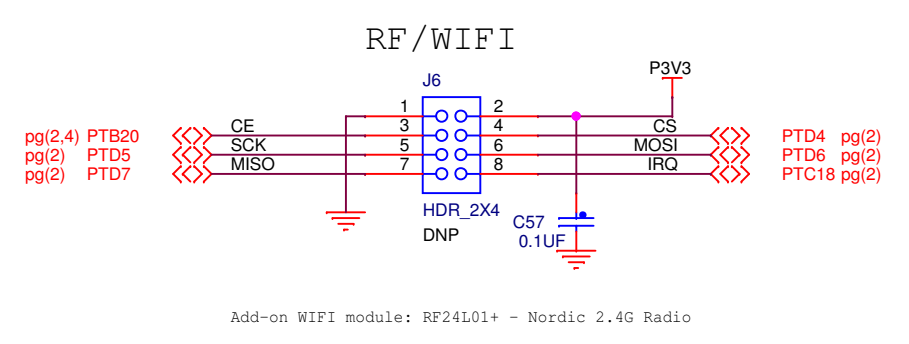
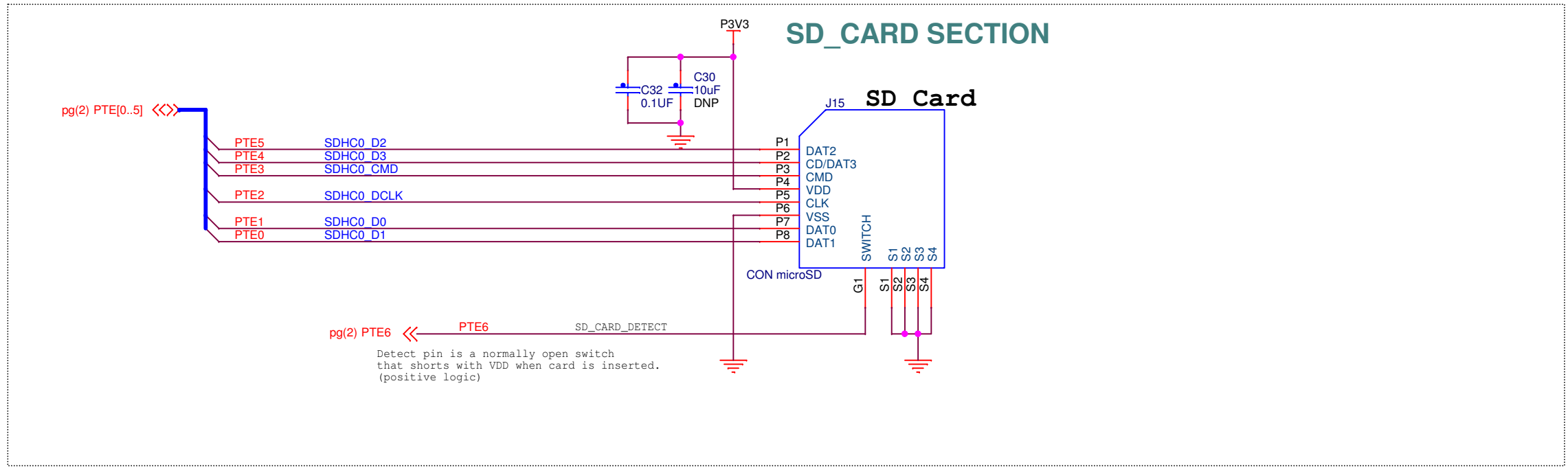
ARDUINO COMPATIBLE HEADERS



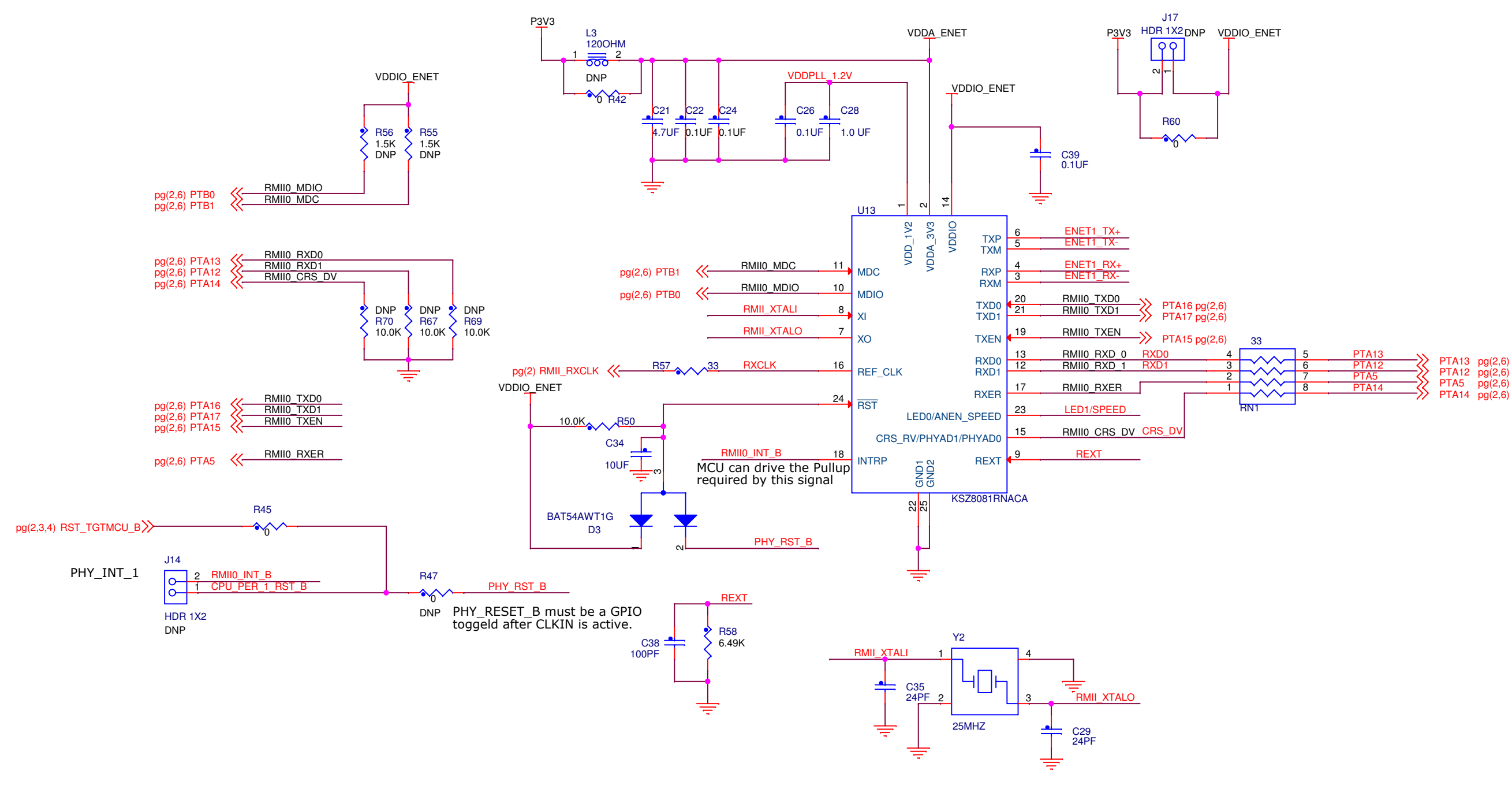
**I2C INERTIAL SENSOR
(ACCELEROMETER AND MAGNETOMETER)**



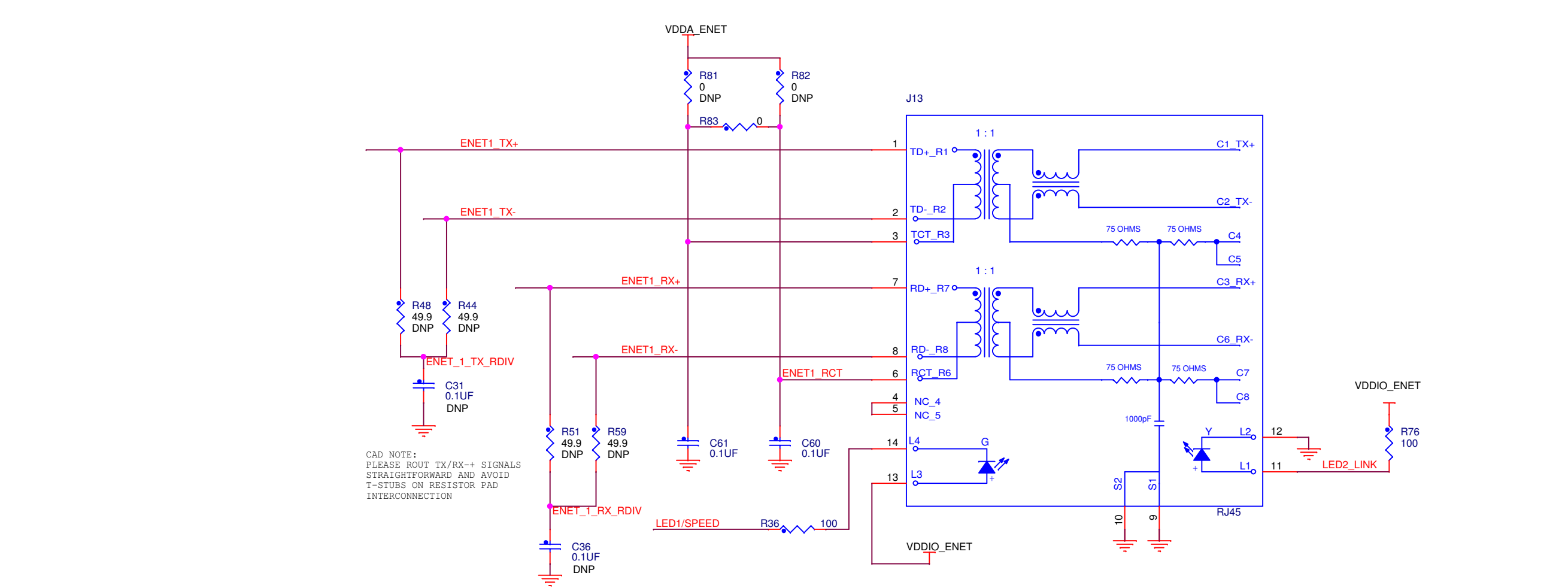
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Drawing Title: FRDM-K64F		
Page Title: ARDUINO SHIELDS & COMBO SENSOR		
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LAYOUT NOTES:
 1. The TRD+/TRD- pairs should be routed with a 100ohm differential impedance and a 50ohm single ended (characteristic) impedance.
 2. The trace lengths within a TRD+/TRD- differential pair should be matched.
 3. The distance between each TRD+/TRD- differential pair should be 50mils or more.



CAD NOTE:
 PLEASE ROUT TX/RX+ SIGNALS STRAIGHTFORWARD AND AVOID T-STUBS ON RESISTOR PAD INTERCONNECTION

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